

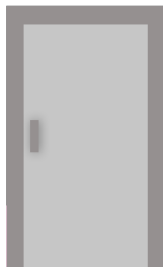
Robust probability updating

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UvA

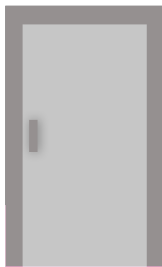
June 7, 2016

Monty Hall's game show

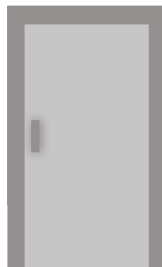


Initial probability:

$1/3$

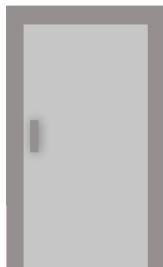


$1/3$

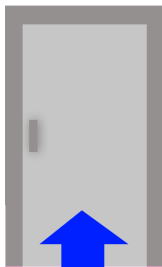


$1/3$

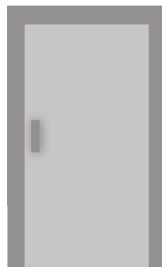
Monty Hall's game show



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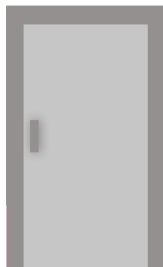


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Monty Hall's game show

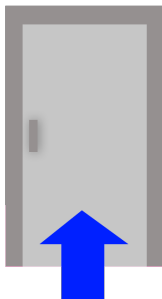


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$1/3$

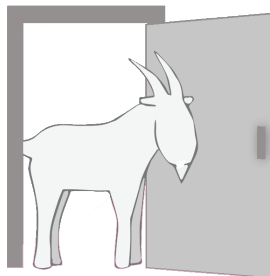
New probability:

?



$1/3$

?



$1/3$

0

Formalizing the problem

Step 1 **Outcome** X is randomly drawn from $\mathcal{X} = \{x_1, x_2, x_3\}$ (the three doors) according to the uniform distribution p

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Step 2 The quizmaster, knowing X , chooses a set $Y \in \mathcal{Y} = \{\{x_1, x_2\}, \{x_2, x_3\}\}$ such that $Y \ni X$

- The structure of \mathcal{Y} reflects that the quizmaster will always open one door, but never the door the contestant picked
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- Step 3** The contestant sees Y but not X , and responds with a **prediction** Q : his estimate of the current probability distribution over \mathcal{X}

Generalizing the problem

We also want to know what probabilities to assign to the outcomes in a more general situation:

- For arbitrary (but finite) outcome spaces \mathcal{X} ;
- For arbitrary marginal distribution p ;
- For arbitrary families of allowed messages \mathcal{Y} .

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- The quizmaster may use randomness when deciding which message Y to give us
- However, we don't know what distribution $P(Y | X)$ he uses
- The conditional distribution P together with the marginal distribution p on \mathcal{X} gives a joint distribution:

Quizmaster uses fair coin:

P	x_1	x_2	x_3
$\{x_1, x_2\}$	1/3	1/6	—
$\{x_2, x_3\}$	—	1/6	1/3
p_x	1/3	1/3	1/3

Quizmaster always opens x_3 :

P	x_1	x_2	x_3
$\{x_1, x_2\}$	1/3	1/3	—
$\{x_2, x_3\}$	—	0	1/3
p_x	1/3	1/3	1/3

Worst-case approach

- We don't want to assume anything about how the quizmaster decides what message to give us
 - In the case of the original Monty Hall game, the fair-coin assumption can be defended based on the symmetry of the problem, but there may not be any symmetry in the general case
- Worst-case approach: we want to give guarantees on our predictions that hold no matter what mechanism is used to choose the message
- Corresponds to a two-player zero-sum **game** between the contestant and the quizmaster, where the quizmaster tries to make the contestant's prediction task as hard as possible

- To do this, we need some way of quantifying how good a prediction is
- We use a **loss function** that maps actual outcome x and contestant's prediction Q to some loss value for the contestant
- Examples:

Logarithmic loss: $L(x, Q) = -\log Q(x)$

Brier loss: $L(x, Q) = \sum_{x' \in \mathcal{X}} (Q(x') - \mathbf{1}_{x'=x})^2$

Randomized 0–1 loss: $L(x, Q) = 1 - Q(x)$

- The value of the game is

$$\sum_{x \in \mathcal{X}} \sum_{y \in \mathcal{Y}} P(x, y) L(x, Q_y)$$

- The contestant chooses $(Q_y)_{y \in \mathcal{Y}}$ to minimize this; the quizmaster chooses P to maximize this
- For many loss functions, this game has a **Nash equilibrium**: there exists a pair of strategies for both players such that neither player would improve their situation by changing their strategy

- We proved optimality conditions for a very general class of loss functions
- For the special case that L is logarithmic loss, the characterization of optimality takes a very nice form:

Theorem

For logarithmic loss, a joint distribution P^ is optimal for the quizmaster if and only if there exists a vector $q \in [0, 1]^{\mathcal{X}}$ such that*

$$q_x = P^*(x | y) \text{ for all } x \in y \in \mathcal{Y} \text{ with } P^*(y) > 0, \text{ and}$$
$$\sum_{x \in y} q_x \leq 1 \text{ for all } y \in \mathcal{Y}$$

- We call this condition on P^* the **RCAR condition**

Optimal strategy may depend on the loss function

P	x_1	x_2	x_3	x_4
$\{x_1, x_2\}$	1/3	1/6	—	—
$\{x_2, x_3\}$	—	1/6	1/6	1/6
p_x	1/3	1/3	1/6	1/6

- This strategy P is optimal for logarithmic loss (it satisfies the RCAR condition), but not for Brier loss

RCAR condition beyond log loss

- If the set of available messages \mathcal{Y} forms a graph (meaning that each message contains exactly two outcomes), then the RCAR condition characterizes optimality **regardless of the loss function**;
- If \mathcal{Y} forms a matroid (satisfies the matroid basis exchange property), then the same is true;
- For any other \mathcal{Y} , this is **not** the case: there exists some marginal p such that the optimal strategies for log loss and Brier loss are different

- Worst-case optimal probability updating gives us a general framework that we can use to **update our beliefs** about an outcome in situations where the joint distribution of outcome and evidence is unknown
- In general, the answer depends on the loss function (“**subjective**”), but in certain situations they don't (“**objective**”)